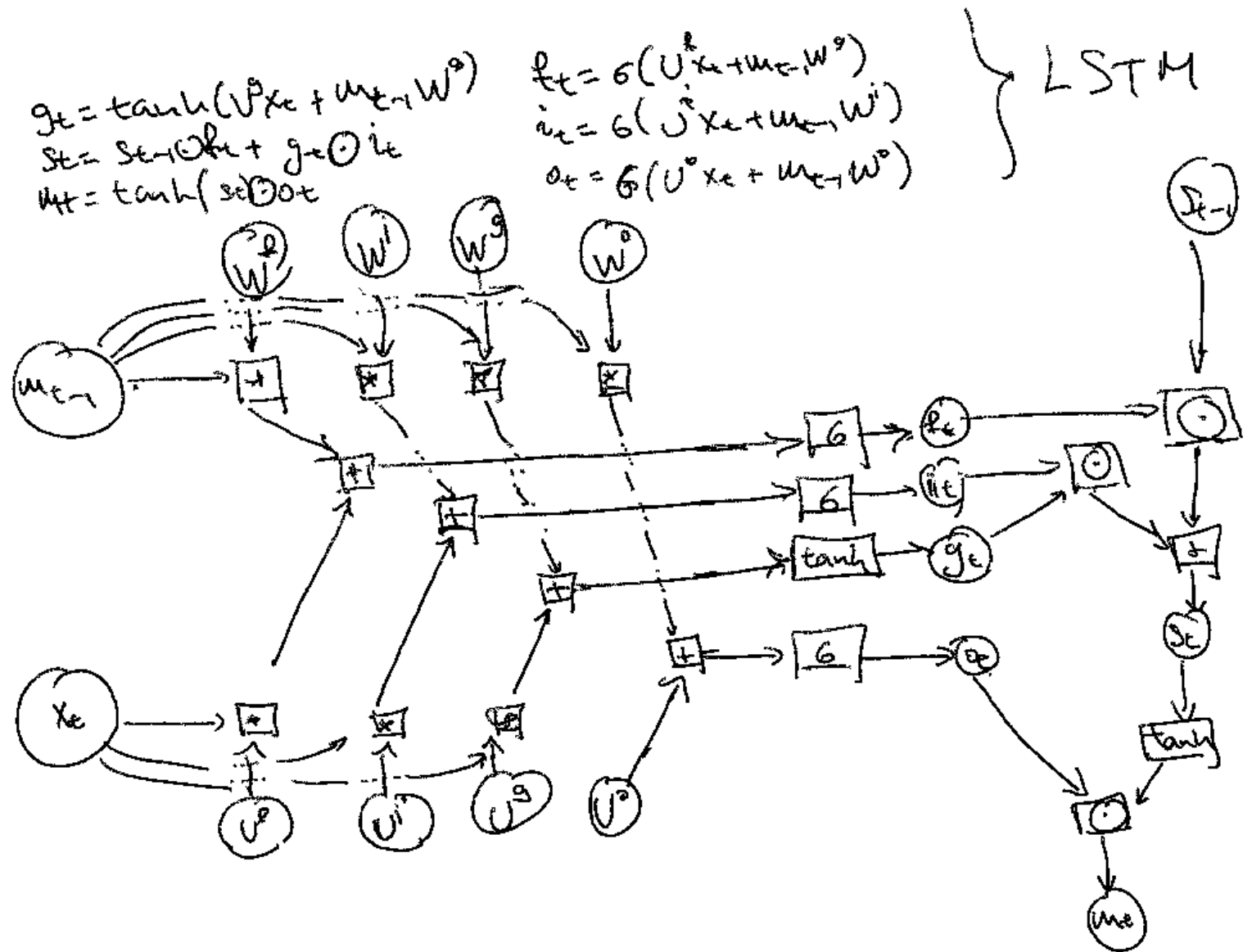


LSTM and variants



Recap: vanishing gradients in RNNs

- RNN equations

$$\mathbf{s}_t = \tanh(U \cdot \mathbf{x}_t + W \cdot \mathbf{s}_{t-1})$$

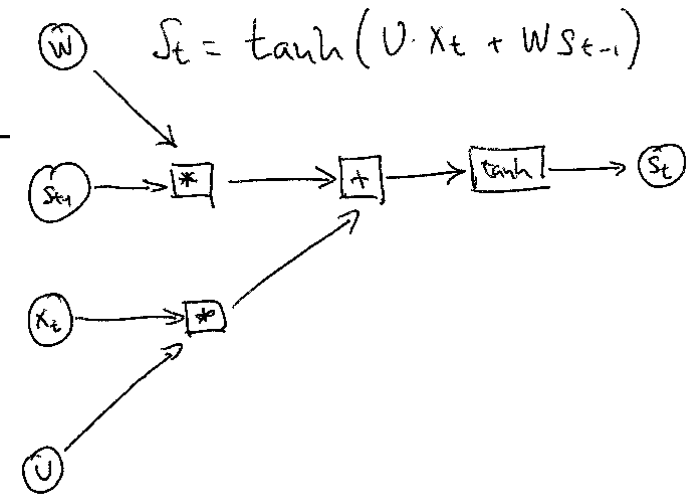
- The RNN gradient of the memory parameters

$$\frac{\partial \mathcal{L}_t}{\partial \mathbf{W}} = \sum_{i=0}^t \frac{\partial \mathcal{L}_t}{\partial y_t} \frac{\partial y_t}{\partial \mathbf{s}_t} \left(\prod_{j=i+1}^t \frac{\partial \mathbf{s}_j}{\partial \mathbf{s}_{j-1}} \right) \frac{\partial \mathbf{s}_i}{\partial \mathbf{W}}$$

- Chain multiplications: $\frac{\partial \mathbf{s}_j}{\partial \mathbf{s}_{j-1}} < 1 \rightarrow$ vanishing gradients

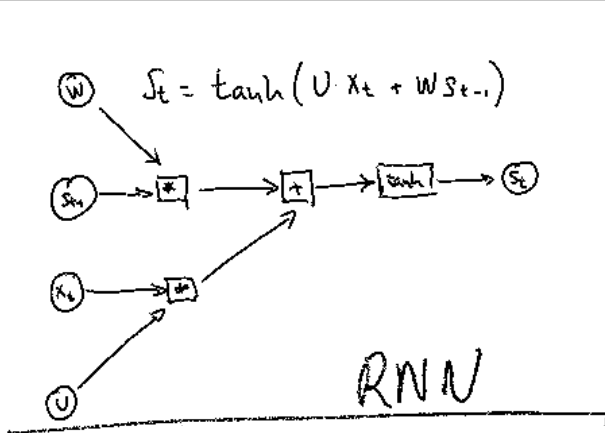
RNN → LSTM: Key idea

$$y_t = \text{softmax}(\mathbf{V} \cdot \mathbf{s}_t)$$
$$\mathbf{s}_t = \tanh(\mathbf{U} \cdot \mathbf{x}_t + \mathbf{W} \cdot \mathbf{s}_{t-1})$$



- Setting $\frac{\partial s_j}{\partial s_{j-1}} = 1 \rightarrow$ no vanishing and exploding gradients
- Remove immediate nonlinear relation between s_t and s_{t-1}
 - Replace **tanh** between s_t and s_{t-1} with identity
- Also, avoid continuous overwriting of state
 - **Modulate** the importance of new input by a gate
 - **Modulate** the importance of new output by a gate
 - **Modulate** the importance of past memories by a gate

Designing an LSTM



$$g_t = U \cdot x_t + W s_{t-1}$$

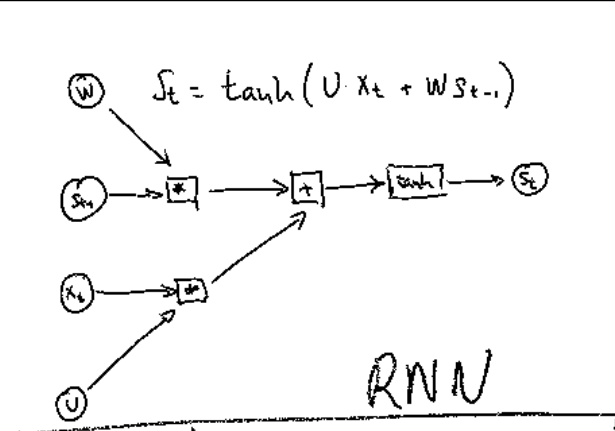
$$s_t = \tanh(g_t)$$

1. Drop nonlinearity between s_t and s_{t-1}

$$g_t = U \cdot x_t + W s_{t-1}$$

$$s_t = g_t$$

Designing an LSTM



RNN

$$g_t = U \cdot x_t + W s_{t-1}$$

$$s_t = \tanh(g_t)$$

1. Drop nonlinearity between s_t and s_{t-1}

$$g_t = U \cdot x_t + W s_{t-1}$$

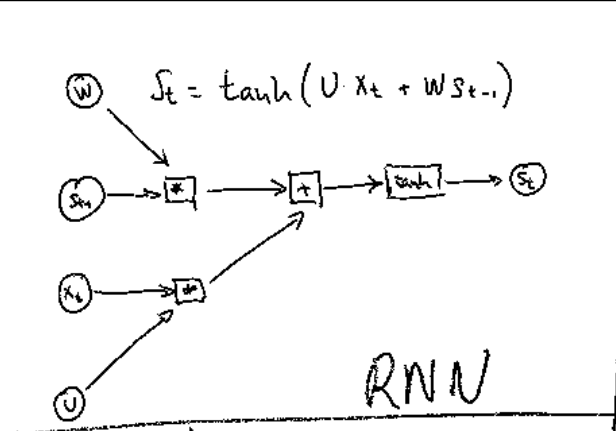
$$s_t = g_t$$

2. Now there is no nonlinearity in the neural network. Not good.
Add a nonlinearity to the term that does not depend on s_{t-1}

$$g_t = \tanh(U x_t)$$

$$s_t = s_{t-1} + g_t$$

Designing an LSTM



$$g_t = U \cdot x_t + W s_{t-1}$$

$$s_t = \tanh(g_t)$$

1. Drop nonlinearity between s_t and s_{t-1}

$$g_t = U \cdot x_t + W s_{t-1}$$

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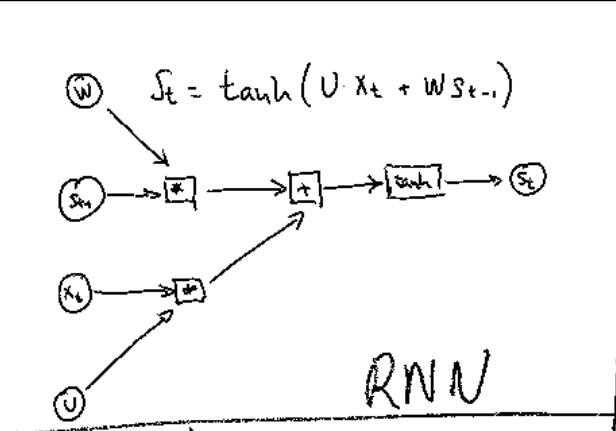
$$s_t = s_{t-1} + g_t$$

3. No vanishing gradients, but also no way to modulate input/memory
Add different gates to modulate (attend with) (0,1) values the key variable

$$g_t = \tanh(U^g x_t) \quad f_t = \sigma(U^f x_t)$$

$$s_t = s_{t-1} \odot f_t + g_t \odot i_t \quad i_t = \sigma(U^i x_t)$$

Designing an LSTM



$$g_t = U \cdot x_t + W s_{t-1}$$

$$s_t = \tanh(g_t)$$

1. Drop nonlinearity between s_t and s_{t-1}

$$g_t = U \cdot x_t + W s_{t-1}$$

$$s_t = g_t$$

2. Now there is no nonlinearity in the neural network. Not good.
Add a nonlinearity to the term that does not depend on s_{t-1}

$$g_t = \tanh(U x_t)$$

$$s_t = s_{t-1} + g_t$$

3. No vanishing gradients, but also no way to moderate input/memory
Add different gate to moderate (attenuate) with (0,1) values the key variable

$$g_t = \tanh(U^g x_t) \quad f_t = \sigma(U^f x_t)$$

$$s_t = s_{t-1} \odot f_t + g_t \odot i_t \quad i_t = \sigma(U^i x_t)$$

4. All good, but the output plays no role in the modulation. Add an output variable

$$g_t = \tanh(U^g x_t + u_{t-1} W^g) \quad f_t = \sigma(U^f x_t + u_{t-1} W^f)$$

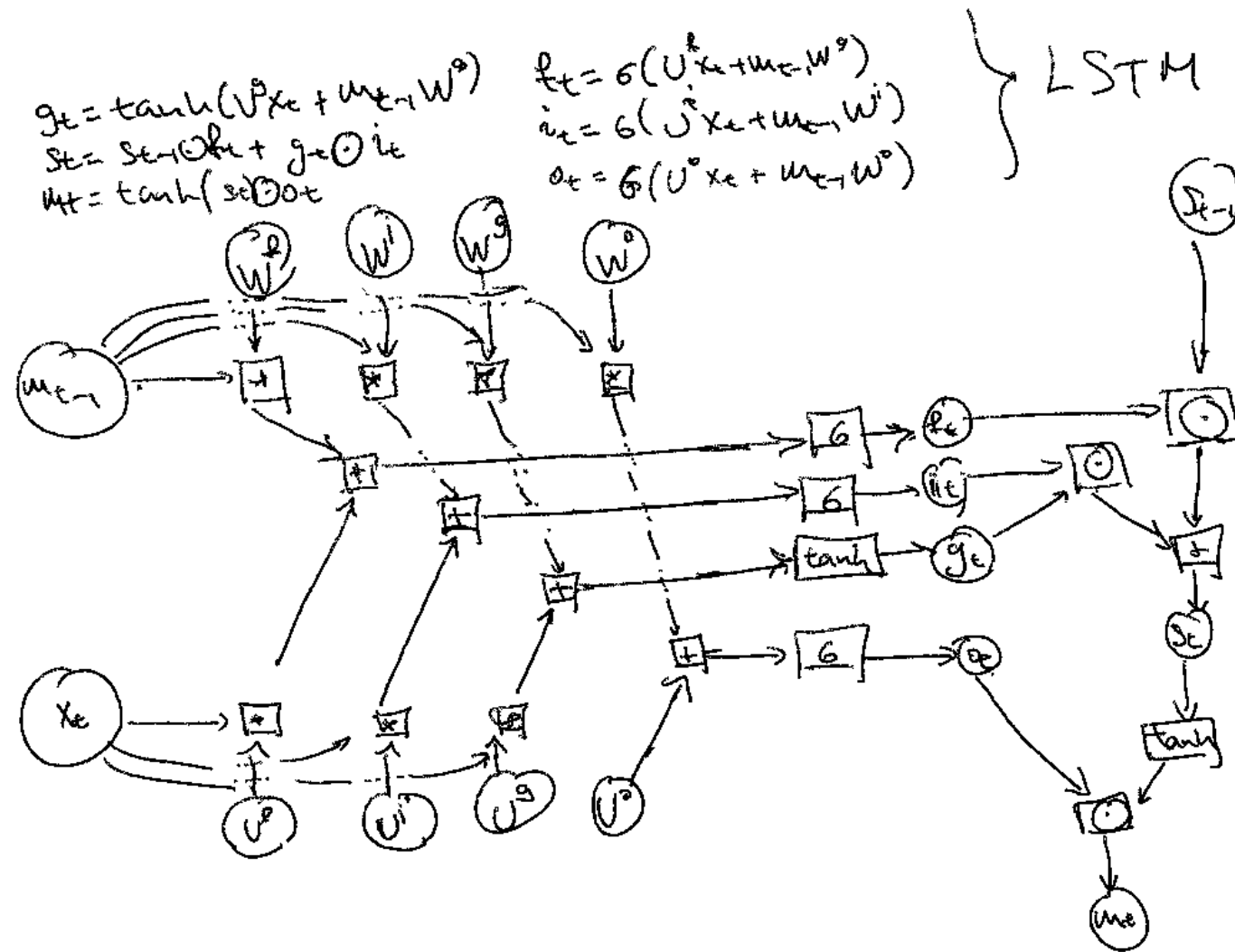
$$s_t = s_{t-1} \odot f_t + g_t \odot i_t \quad i_t = \sigma(U^i x_t + u_{t-1} W^i)$$

$$u_t = \tanh(s_t) \odot o_t$$

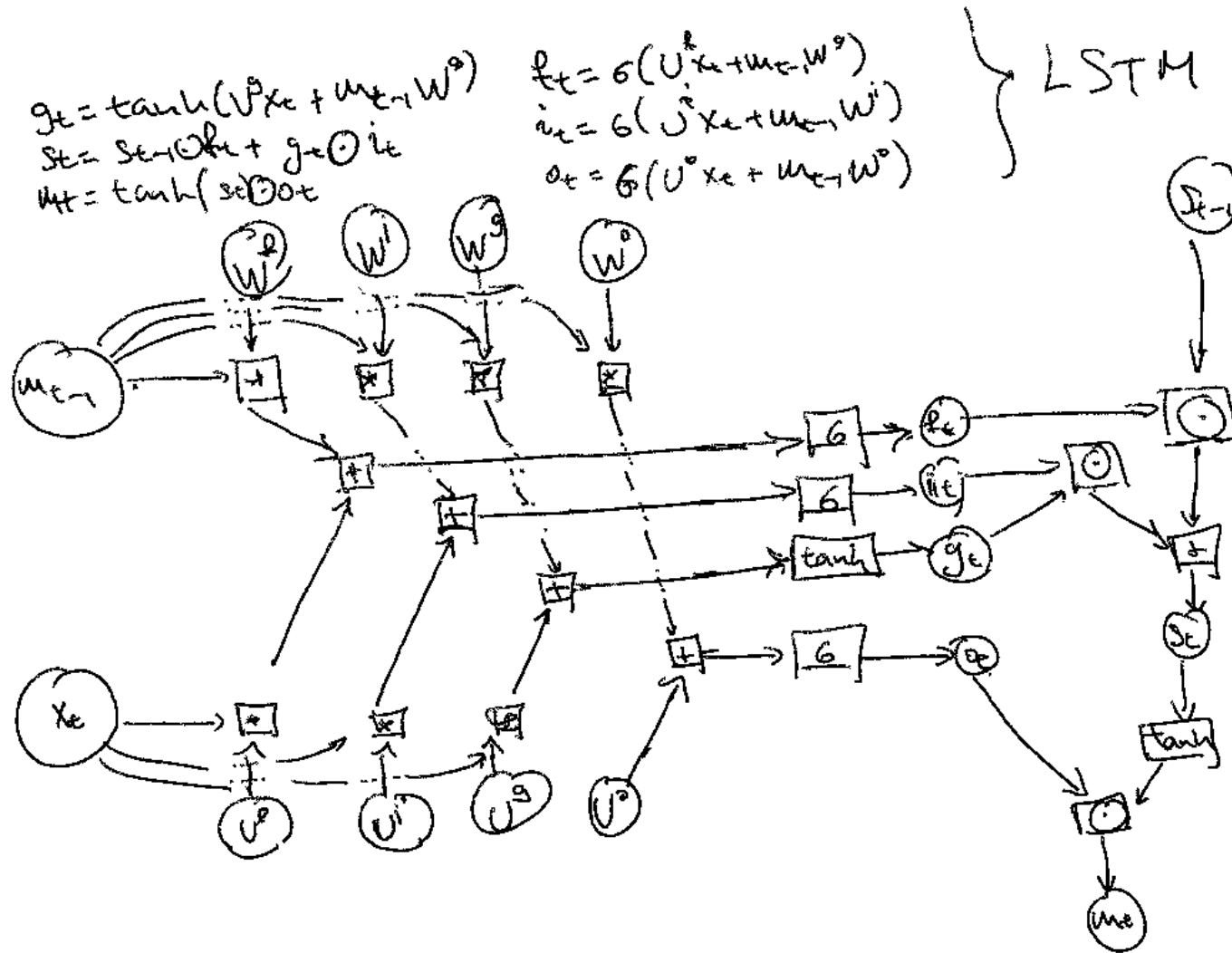
$$o_t = \sigma(U^o x_t + u_{t-1} W^o)$$

} LSTM

An LSTM, graphically



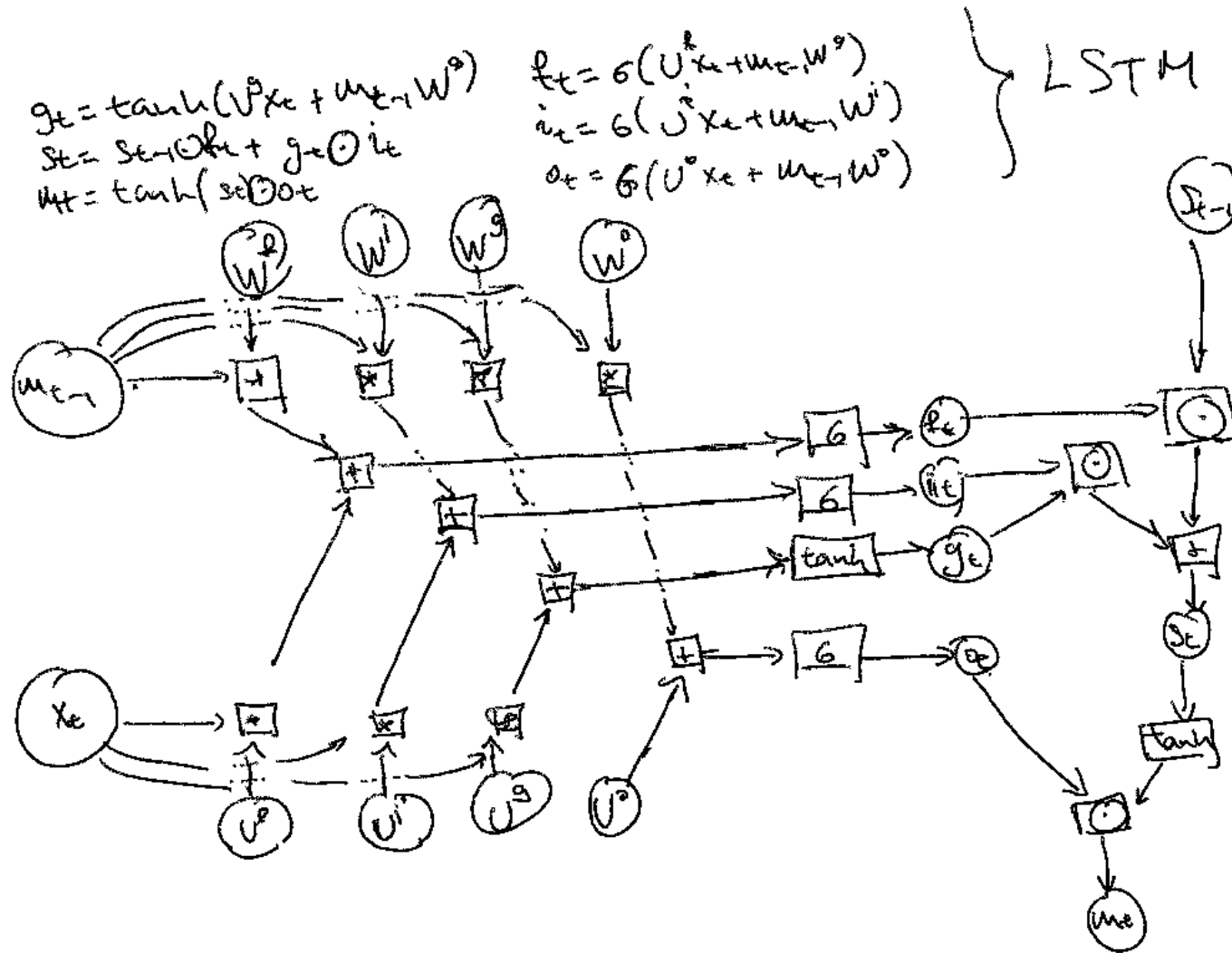
LSTM: Forward propagation step by step



LSTM speaking

How important is my input?

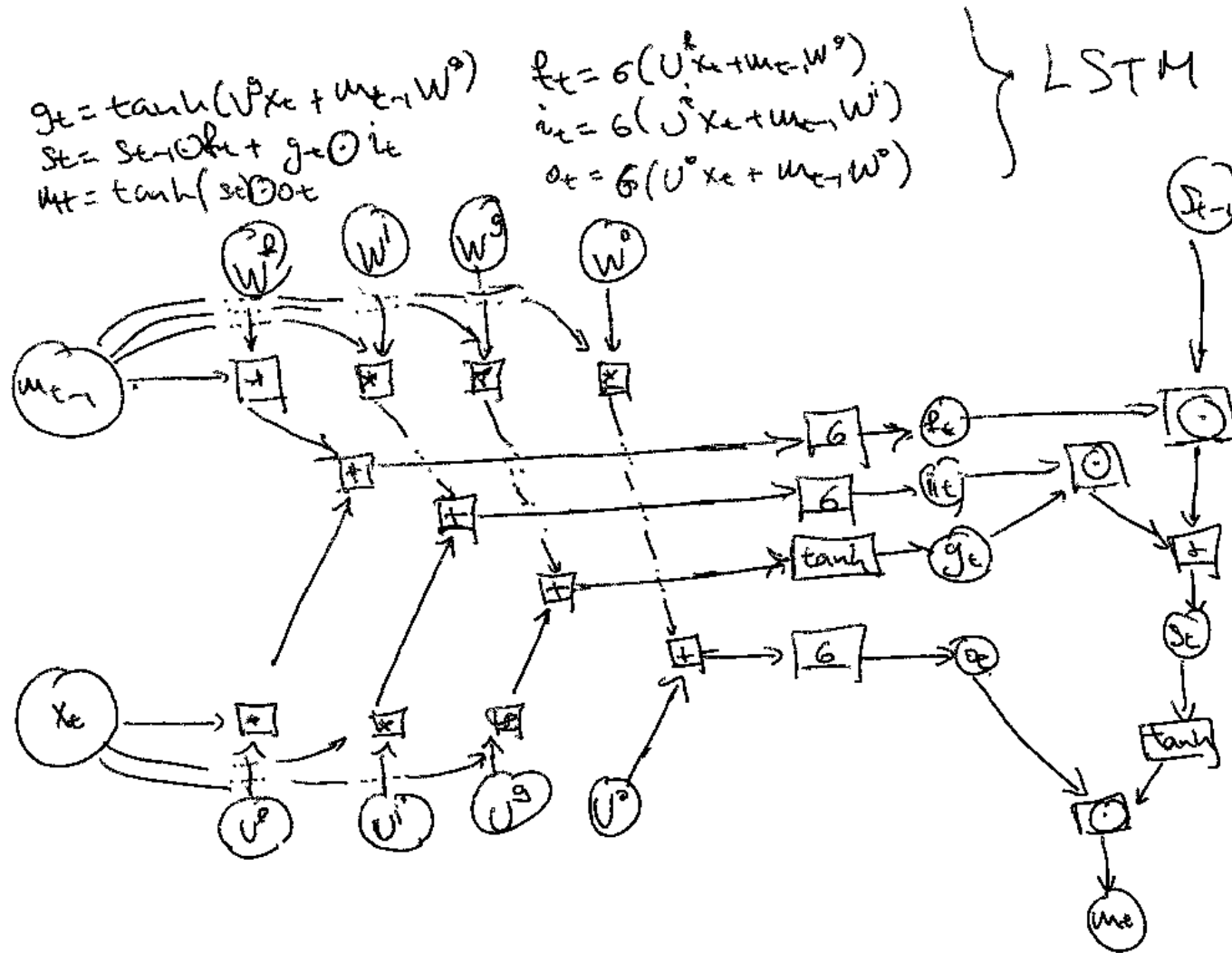
LSTM: Forward propagation step by step



LSTM speaking

How important is my past state?

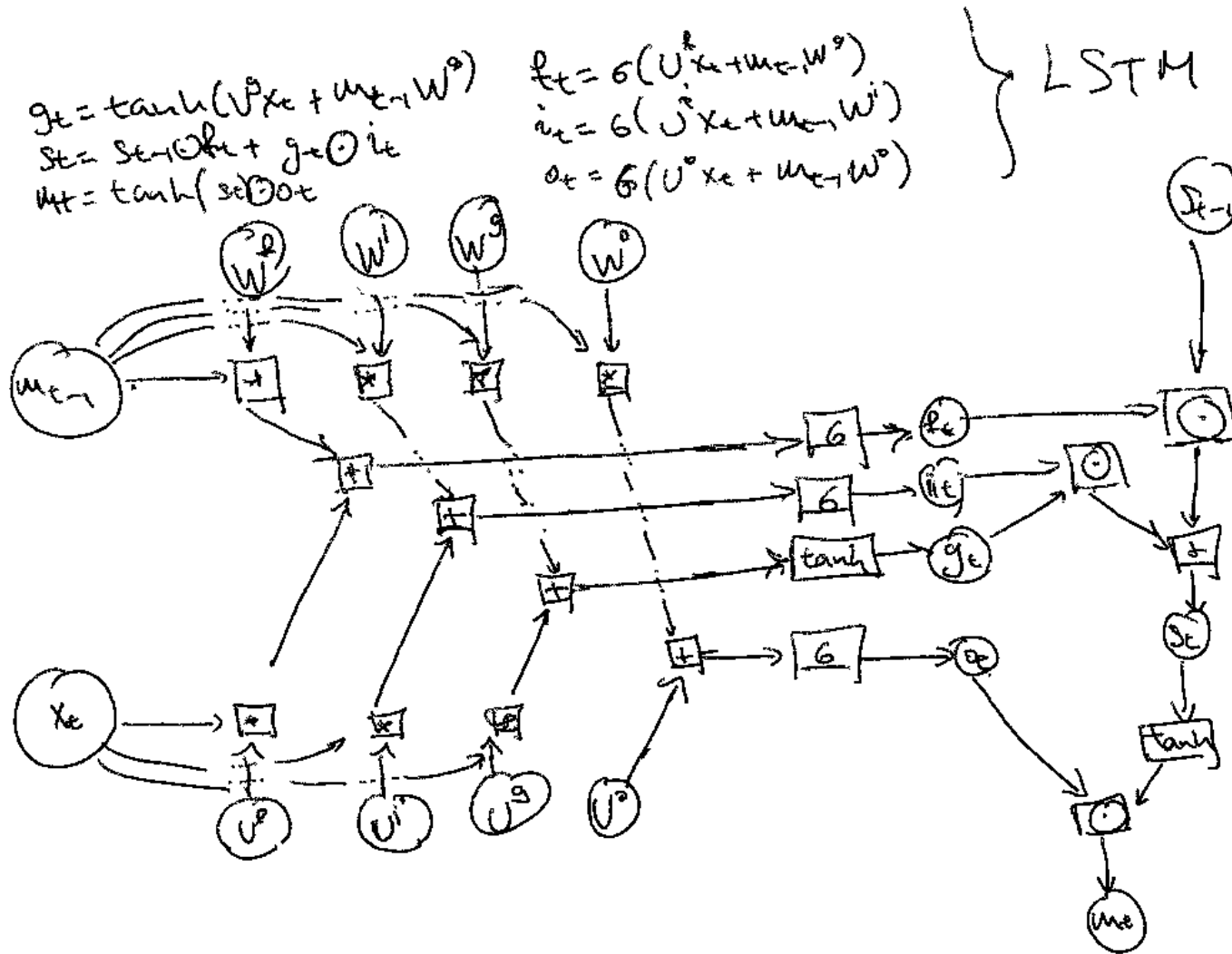
LSTM: Forward propagation step by step



LSTM speaking

What could be a relevant new memory?

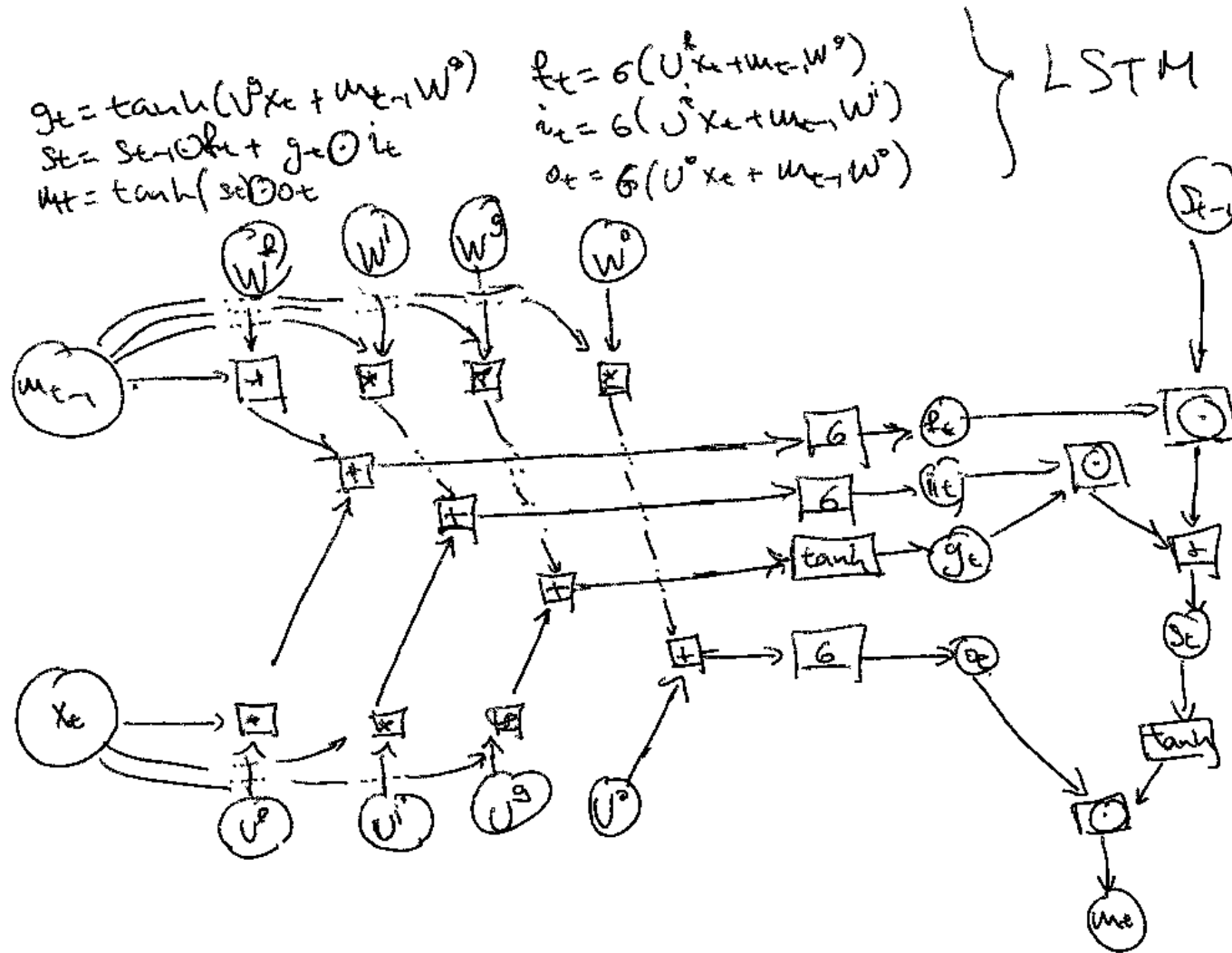
LSTM: Forward propagation step by step



LSTM speaking

Ok, let's compute my new state

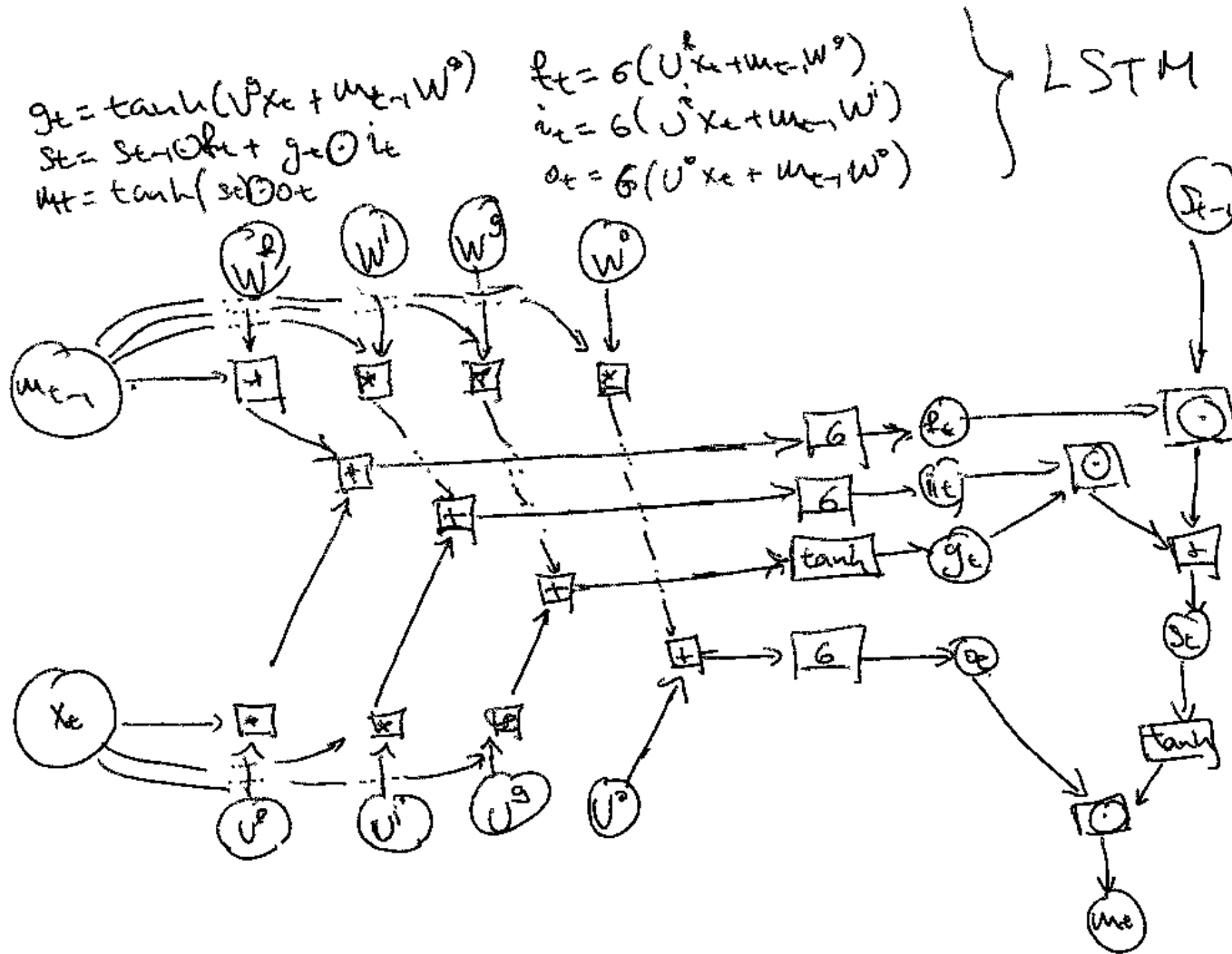
LSTM: Forward propagation step by step



LSTM speaking

Is my new state useful for output?
Check first how important is to
give an output.

LSTM: Forward propagation step by step



LSTM speaking

What is my new output?

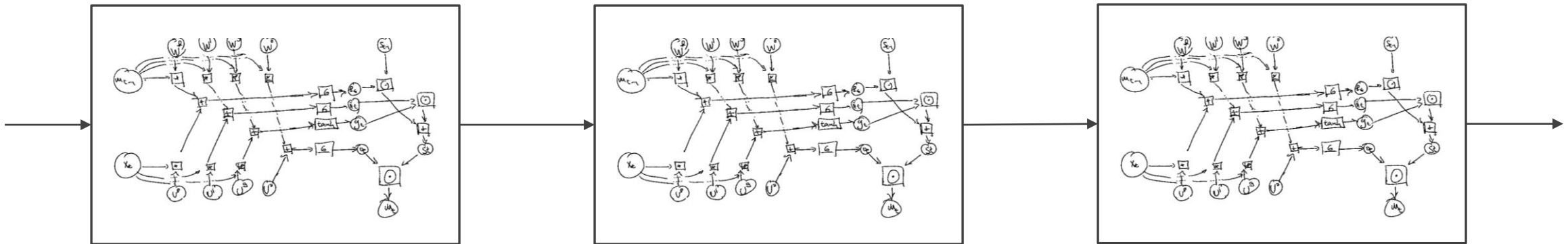
LSTM insights

- Comparing the state equations between RNN and LSTM
 - RNN: $\mathbf{s}_t = \tanh(U \cdot \mathbf{x}_t + W \cdot \mathbf{s}_{t-1})$
 - LSTM: $\mathbf{s}_t = \mathbf{s}_{t-1} \odot \mathbf{f}_t + \mathbf{g}_t \odot \mathbf{i}_t$, $\mathbf{m}_t = \tanh(\mathbf{s}_t) \odot \mathbf{o}_t$
- The LSTM also has indirect nonlinear relation between \mathbf{s}_t and \mathbf{s}_{t-1} via \mathbf{m}_t
 - There is also direct linear relation \rightarrow Strong gradients encouraged
- Use sigmoids for gating/squashing \rightarrow (0,1) values
 - Use tanh as module's recurrence nonlinearity, instead

Nice tutorial: <http://colah.github.io/posts/2015-08-Understanding-LSTMs/>

Unrolling the LSTMs

- Just the same like for RNNs
- The internal equations are more complicated but the idea is the same
- Because of linear relation between s_t and s_{t-1} vanishing gradients mitigated
 - LSTM captures short-term, as well as long-term correlations



LSTM variants

- LSTM with peephole connections
- Gates have access also to the previous cell states c_{t-1} (not only memories)
- Bi-directional recurrent networks
- Gated Recurrent Units (GRU)
- Phased LSTMs
- Skip LSTMs
- And many more ...